The Derivative as a Rate of Change

In Section 2.1, we initiated the study of average and instantaneous rates of change. In this section, we continue our investigations of applications in which derivatives are used to model the rates at which things change in the world around us. We revisit the study of motion along a line and examine other applications.

It is natural to think of change as change with respect to time, but other variables can be treated in the same way. For example, a physician may want to know how change in dosage affects the body’s response to a drug. An economist may want to study how the cost of producing steel varies with the number of tons produced.

Instantaneous Rates of Change

If we interpret the difference quotient \( \frac{f(x + h) - f(x)}{h} \) as the average rate of change in \( f \) over the interval from \( x \) to \( x + h \), we can interpret its limit as \( h \to 0 \) as the rate at which \( f \) is changing at the point \( x \).

**DEFINITION** Instantaneous Rate of Change

The *instantaneous rate of change* of \( f \) with respect to \( x \) at \( x_0 \) is the derivative

\[
f'(x_0) = \lim_{h \to 0} \frac{f(x_0 + h) - f(x_0)}{h},
\]

provided the limit exists.

Thus, instantaneous rates are limits of average rates.

It is conventional to use the word *instantaneous* even when \( x \) does not represent time. The word is, however, frequently omitted. When we say *rate of change*, we mean *instantaneous rate of change*. 
EXAMPLE 1  How a Circle’s Area Changes with Its Diameter

The area \( A \) of a circle is related to its diameter by the equation

\[ A = \frac{\pi}{4} D^2. \]

How fast does the area change with respect to the diameter when the diameter is 10 m?

**Solution**  The rate of change of the area with respect to the diameter is

\[ \frac{dA}{dD} = \frac{\pi}{2}. \]

When \( D = 10 \) m, the area is changing at rate \((\pi/2)10 = 5\pi \) m\(^2\)/m.

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**Motion Along a Line: Displacement, Velocity, Speed, Acceleration, and Jerk**

Suppose that an object is moving along a coordinate line (say an \( s \)-axis) so that we know its position \( s \) on that line as a function of time \( t \):

\[ s = f(t). \]

The displacement of the object over the time interval from \( t \) to \( t + \Delta t \) (Figure 3.12) is

\[ \Delta s = f(t + \Delta t) - f(t), \]

and the average velocity of the object over that time interval is

\[ v_{av} = \frac{\text{displacement}}{\text{travel time}} = \frac{\Delta s}{\Delta t} = \frac{f(t + \Delta t) - f(t)}{\Delta t}. \]

To find the body’s velocity at the exact instant \( t \), we take the limit of the average velocity over the interval from \( t \) to \( t + \Delta t \) as \( \Delta t \) shrinks to zero. This limit is the derivative of \( f \) with respect to \( t \).

**DEFINITION**  **Velocity**

**Velocity** (instantaneous velocity) is the derivative of position with respect to time. If a body’s position at time \( t \) is \( s = f(t) \), then the body’s velocity at time \( t \) is

\[ v(t) = \frac{ds}{dt} = \lim_{\Delta t \to 0} \frac{f(t + \Delta t) - f(t)}{\Delta t}. \]

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**EXAMPLE 2**  Finding the Velocity of a Race Car

Figure 3.13 shows the time-to-distance graph of a 1996 Riley & Scott Mk III-Olds WSC race car. The slope of the secant \( PQ \) is the average velocity for the 3-sec interval from \( t = 2 \) to \( t = 5 \) sec; in this case, it is about 100 ft/sec or 68 mph.

The slope of the tangent at \( P \) is the speedometer reading at \( t = 2 \) sec, about 57 ft/sec or 39 mph. The acceleration for the period shown is a nearly constant 28.5 ft/sec\(^2\) during
each second, which is about 0.89g, where g is the acceleration due to gravity. The race car's top speed is an estimated 190 mph. (Source: Road and Track, March 1997.)

Besides telling how fast an object is moving, its velocity tells the direction of motion. When the object is moving forward (s increasing), the velocity is positive; when the body is moving backward (s decreasing), the velocity is negative (Figure 3.14).

If we drive to a friend's house and back at 30 mph, say, the speedometer will show 30 on the way over but it will not show −30 on the way back, even though our distance from home is decreasing. The speedometer always shows speed, which is the absolute value of velocity. Speed measures the rate of progress regardless of direction.
EXAMPLE 3  Horizontal Motion

Figure 3.15 shows the velocity $v = f'(t)$ of a particle moving on a coordinate line. The particle moves forward for the first 3 sec, moves backward for the next 2 sec, stands still for a second, and moves forward again. The particle achieves its greatest speed at time $t = 4$, while moving backward.

The rate at which a body’s velocity changes is the body’s acceleration. The acceleration measures how quickly the body picks up or loses speed.

A sudden change in acceleration is called a jerk. When a ride in a car or a bus is jerky, it is not that the accelerations involved are necessarily large but that the changes in acceleration are abrupt.
Near the surface of the Earth all bodies fall with the same constant acceleration. Galileo's experiments with free fall (Example 1, Section 2.1) lead to the equation

\[ s = \frac{1}{2} gt^2, \]

where \( s \) is distance and \( g \) is the acceleration due to Earth's gravity. This equation holds in a vacuum, where there is no air resistance, and closely models the fall of dense, heavy objects, such as rocks or steel tools, for the first few seconds of their fall, before air resistance starts to slow them down.

The value of \( g \) in the equation depends on the units used to measure \( t \) and \( s \). With \( t \) in seconds (the usual unit), the value of \( g \) determined by measurement at sea level is approximately (feet per second squared) in English units, and \( g = 9.8 \text{ m/sec}^2 \) (meters per second squared) in metric units. (These gravitational constants depend on the distance from Earth's center of mass, and are slightly lower on top of Mt. Everest, for example.)

The jerk of the constant acceleration of gravity is zero:

\[ j(t) = \frac{da}{dt} = \frac{d^2 s}{dt^2}. \]

An object does not exhibit jerkiness during free fall.

**EXAMPLE 4** Modeling Free Fall

Figure 3.16 shows the free fall of a heavy ball bearing released from rest at time \( t = 0 \) sec.

(a) How many meters does the ball fall in the first 2 sec?

(b) What is its velocity, speed, and acceleration then?

**Solution**

(a) The metric free-fall equation is \( s = 4.9t^2 \). During the first 2 sec, the ball falls

\[ s(2) = 4.9(2)^2 = 19.6 \text{ m}. \]

(b) At any time \( t \), velocity is the derivative of position:

\[ v(t) = s'(t) = \frac{d}{dt}(4.9t^2) = 9.8t. \]
EXAMPLE 5 Modeling Vertical Motion

A dynamite blast blows a heavy rock straight up with a launch velocity of 160 ft/sec (about 109 mph) (Figure 3.17a). It reaches a height of after \( t \) sec.

(a) How high does the rock go?

(b) What are the velocity and speed of the rock when it is 256 ft above the ground on the way up? On the way down?

(c) What is the acceleration of the rock at any time \( t \) during its flight (after the blast)?

(d) When does the rock hit the ground again?

Solution

(a) In the coordinate system we have chosen, \( s \) measures height from the ground up, so the velocity is positive on the way up and negative on the way down. The instant the rock is at its highest point is the one instant during the flight when the velocity is 0. To find the maximum height, all we need to do is to find when \( s' = 0 \) and evaluate \( s \) at this time.

At any time \( t \), the velocity is

\[ \frac{ds}{dt} = 160 - 32t \]

The velocity is zero when

\[ 160 - 32t = 0 \quad \text{or} \quad t = 5 \text{ sec}. \]

The rock’s height at \( t = 5 \) sec is

\[ s_{\text{max}} = s(5) = 160(5) - 16(5)^2 = 800 - 400 = 400 \text{ ft}. \]

(b) To find the rock’s velocity at 256 ft on the way up and again on the way down, we first find the two values of \( t \) for which

\[ s(t) = 160t - 16t^2 = 256. \]

To solve this equation, we write

\[ 16t^2 - 160t + 256 = 0 \]
\[ 16(t^2 - 10t + 16) = 0 \]
\[ (t - 2)(t - 8) = 0 \]

\[ t = 2 \text{ sec}, \ t = 8 \text{ sec}. \]
The rock is 256 ft above the ground 2 sec after the explosion and again 8 sec after the explosion. The rock’s velocities at these times are

\[ v(2) = 160 - 32(2) = 160 - 64 = 96 \text{ ft/sec}. \]
\[ v(8) = 160 - 32(8) = 160 - 256 = -96 \text{ ft/sec}. \]

At both instants, the rock’s speed is 96 ft/sec. Since the rock is moving upward \((s' \text{ is increasing})\) at \(t = 2\) sec; it is moving downward \((s' \text{ is decreasing})\) at \(t = 8\) because \(v(8) < 0\).

(c) At any time during its flight following the explosion, the rock’s acceleration is a constant

\[ a = \frac{dv}{dt} = \frac{d}{dt} (160 - 32t) = -32 \text{ ft/sec}^2. \]

The acceleration is always downward. As the rock rises, it slows down; as it falls, it speeds up.

(d) The rock hits the ground at the positive time \(t\) for which \(s = 0\). The equation \(160t - 16t^2 = 0\) factors to give \(16t(10 - t) = 0\), so it has solutions \(t = 0\) and \(t = 10\). At \(t = 0\), the blast occurred and the rock was thrown upward. It returned to the ground 10 sec later.

### Derivatives in Economics

Engineers use the terms velocity and acceleration to refer to the derivatives of functions describing motion. Economists, too, have a specialized vocabulary for rates of change and derivatives. They call them marginals.

In a manufacturing operation, the cost of production \(c(x)\) is a function of \(x\), the number of units produced. The marginal cost of production is the rate of change of cost with respect to level of production, so it is \(dc/dx\).

Suppose that \(c(x)\) represents the dollars needed to produce \(x\) tons of steel in one week. It costs more to produce \(x + h\) units per week, and the cost difference, divided by \(h\), is the average cost of producing each additional ton:

\[ \frac{c(x + h) - c(x)}{h} = \text{average cost of each of the additional} \]
\[ \text{\(h\) tons of steel produced}. \]

The limit of this ratio as \(h \to 0\) is the marginal cost of producing more steel per week when the current weekly production is \(x\) tons (Figure 3.18).

\[ \frac{dc}{dx} = \lim_{h \to 0} \frac{c(x + h) - c(x)}{h} = \text{marginal cost of production}. \]

Sometimes the marginal cost of production is loosely defined to be the extra cost of producing one unit:

\[ \frac{\Delta c}{\Delta x} = \frac{c(x + 1) - c(x)}{1}, \]

which is approximated by the value of \(dc/dx\) at \(x\). This approximation is acceptable if the slope of the graph of \(c\) does not change quickly near \(x\). Then the difference quotient will be close to its limit \(dc/dx\), which is the rise in the tangent line if \(\Delta x = 1\) (Figure 3.19). The approximation works best for large values of \(x\).
Economists often represent a total cost function by a cubic polynomial

\[ c(x) = \alpha x^3 + \beta x^2 + \gamma x + \delta \]

where \( \delta \) represents fixed costs such as rent, heat, equipment capitalization, and management costs. The other terms represent variable costs such as the costs of raw materials, taxes, and labor. Fixed costs are independent of the number of units produced, whereas variable costs depend on the quantity produced. A cubic polynomial is usually complicated enough to capture the cost behavior on a relevant quantity interval.

**EXAMPLE 6** Marginal Cost and Marginal Revenue

Suppose that it costs

\[ c(x) = x^3 - 6x^2 + 15x \]

dollars to produce \( x \) radiators when 8 to 30 radiators are produced and that

\[ r(x) = x^3 - 3x^2 + 12x \]

gives the dollar revenue from selling \( x \) radiators. Your shop currently produces 10 radiators a day. About how much extra will it cost to produce one more radiator a day, and what is your estimated increase in revenue for selling 11 radiators a day?

**Solution** The cost of producing one more radiator a day when 10 are produced is about \( c'(10) \):

\[ c'(x) = \frac{d}{dx} (x^3 - 6x^2 + 15x) = 3x^2 - 12x + 15 \]

\[ c'(10) = 3(100) - 12(10) + 15 = 195. \]

The additional cost will be about $195. The marginal revenue is

\[ r'(x) = \frac{d}{dx} (x^3 - 3x^2 + 12x) = 3x^2 - 6x + 12. \]

The marginal revenue function estimates the increase in revenue that will result from selling one additional unit. If you currently sell 10 radiators a day, you can expect your revenue to increase by about

\[ r'(10) = 3(100) - 6(10) + 12 = $252 \]

if you increase sales to 11 radiators a day.

**EXAMPLE 7** Marginal Tax Rate

To get some feel for the language of marginal rates, consider marginal tax rates. If your marginal income tax rate is 28% and your income increases by $1000, you can expect to pay an extra $280 in taxes. This does not mean that you pay 28% of your entire income in taxes. It just means that at your current income level \( I \), the rate of increase of taxes \( T \) with respect to income is \( dT/dI = 0.28 \). You will pay $0.28 out of every extra dollar you earn in taxes. Of course, if you earn a lot more, you may land in a higher tax bracket and your marginal rate will increase.
Sensitivity to Change

When a small change in $x$ produces a large change in the value of a function $f(x)$, we say that the function is relatively sensitive to changes in $x$. The derivative $f'(x)$ is a measure of this sensitivity.

**EXAMPLE 8** Genetic Data and Sensitivity to Change

The Austrian monk Gregor Johann Mendel (1822–1884), working with garden peas and other plants, provided the first scientific explanation of hybridization.

His careful records showed that if $p$ (a number between 0 and 1) is the frequency of the gene for smooth skin in peas (dominant) and $(1 - p)$ is the frequency of the gene for wrinkled skin in peas, then the proportion of smooth-skinned peas in the next generation will be

$$y = 2p(1 - p) + p^2 = 2p - p^2.$$ 

The graph of $y$ versus $p$ in Figure 3.20a suggests that the value of $y$ is more sensitive to a change in $p$ when $p$ is small than when $p$ is large. Indeed, this fact is borne out by the derivative graph in Figure 3.20b, which shows that $dy/dp$ is close to 2 when $p$ is near 0 and close to 0 when $p$ is near 1.

![Figure 3.20](image)

(a) The graph of $y = 2p - p^2$, describing the proportion of smooth-skinned peas.
(b) The graph of $dy/dp$ (Example 8).

The implication for genetics is that introducing a few more dominant genes into a highly recessive population (where the frequency of wrinkled skin peas is small) will have a more dramatic effect on later generations than will a similar increase in a highly dominant population.

\[\blacksquare\]